Capable GV: Capabilities for Session Types in GV

Magdalena J. Latifa¹ and Ornela Dardha¹

¹ University of Glasgow 2398248L@student.gla.ac.uk ² University of Glasgow ornela.dardha@glasgow.ac.uk

Abstract

This is an ongoing work which introduces Capable GV (CGV), a functional calculus with binary session types that utilises capabilities. Capabilities split channels into a linear capability and an unrestricted endpoint, thus allowing channel sharing. Consequently, CGV enjoys greater expressivity and allows cyclic processes at the cost of losing deadlock freedom, which we aim to restore using priorities as in works by Kokke and Dardha [5, 4].

1 Introduction

Good Variation (GV) is a functional calculus with binary session types that allows protocolfollowing concurrent communication and was originally introduced by Wadler [8]. Since then, many extensions to GV have been developed, including Exceptional GV [3], Priority GV [5] and Hypersequent GV [2], with the aim of improving its expressivity and guarantees while taking advantage of the benefits that GV provides: higher-order functions, separation of runtime configuration and a more natural fit for implementations. *Capabilities* [7] are a method of allowing channel sharing. This method relies on splitting channels into two disjoint components, which allows channels to be safely shared. In this work, we develop an extension to GV that allows channel sharing, consequently improving the expressivity of the system.

2 Capable GV

We present the statics of Capable GV (CGV), a GV-based functional language with shareable session types. Channel sharing in CGV is achieved by introducing unrestricted channel endpoints and linear capabilities that are managed by a flow-sensitive type-and-effect system. As linearity is enforced via capabilities, sharing does not violate communication safety. While CGV allows for greater expressivity, it comes at the cost of deadlock-freedom as the system allows cyclic processes. CGV types are defined by the following grammar:

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\begin{array}{rcl} S & \coloneqq & |T.S \ | \ ?T.S \ | \ \mathbf{end} \\ T,U & \coloneqq & T \times U \ | \ T+U \ | \ \mathbf{1} \ | \ tr(\rho) \ | \ [\rho(S)] \ | \ T(C_1) \multimap (C_2) \ U \\ \Gamma,\Delta & \coloneqq & \varnothing \ | \ \Gamma, x : T \\ C & \coloneqq & \varnothing \ | \ C \otimes \rho(S) \end{array}
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Constructs $tr(\rho)$ and $\rho(S)$ are the core of CGV and represent the separation of the channel endpoint and the capability of using it. Tracked type $tr(\rho)$ specifies that the channel endpoint is controlled by capability ρ . Capability ρ exists in a capability set C in the form $\rho(S)$ which specifies the channel's session type S. Additionally, a capability can be packed into a pack type $[\rho(S)]$ and subsequently relayed to another thread. In order to accommodate for capabilities in the type-and-effect system, functions have the type $T(C_1) \multimap (C_2) U$ which denotes a linear Capable GV

function $T \rightarrow U$ where the function body requires pre-evaluation capability set C_1 and produces capability set C_2 when evaluated. The remaining types are standard session types or linear λ calculus types.

CGV terms are defined by the following grammar:

Terms pack V and unpack V are unique to CGV and allow "inactivating" and "reactivating" channels by packing and unpacking capabilities. Terms send V and recv V are standard to GV but they no longer return a copy of the channel since channels are unrestricted. Terms close V, new and spawn M N are analogous to Priority GV's terms [5] with the change of new also creating capabilities for the new channels and spawn requiring a packed capability to initialise the newly spawned thread with. The rest of the terms are standard linear λ -calculus terms.

Typing rules T-Recy and T-Pack demonstrate the behaviour of capabilities in CGV. For T-Recv, in order to receive a message of type T on a channel of type $tr(\rho)$, the capability of using the endpoint $\rho(?T.S)$ needs to be in the pre-evaluation capability set. After this communication takes place, the capability must update the session type; hence the post-evaluation capability set must contain the capability in the form $\rho(S)$. T-Pack specifies the behaviour of packing the capability in order to relay it to another thread. In order to pack the capability of channel of type $tr(\rho)$, the capability $\rho(S)$ needs to be in the pre-evaluation capability set. After the channel is packed, the capability $\rho(S)$ is removed from the capability set and is instead "inactivated" and expressed in the pack type $[\rho(S)]$. The session type of this channel cannot change until the capability is unpacked and the channel becomes active again, which is key to ensuring linearity of communication.

T-Recv

 $\frac{\Gamma \text{-}\operatorname{Recv}}{\Gamma; C \otimes \rho(?T.S) \vdash \operatorname{\mathbf{recv}} V: T \triangleright C \otimes \rho(S)} \qquad \frac{\Gamma \text{-}\operatorname{Pack}}{\Gamma; C \otimes \rho(S) \vdash \operatorname{\mathbf{pack}} V: [\rho(S)] \triangleright C}$

3 **Conclusions and Future Work**

We have presented our work in progress on CGV—Capable GV. At the time of writing, we have completed syntax of types and terms as well as typing rules and we are working on finalising the operational semantics and type safety results. CGV uses capabilities in order to introduce channel sharing and provide greater expressivity. This is achieved via tracking capabilities in a type-and-effect system and making the channel endpoints unrestricted. While this approach allows sharing, it also reintroduces deadlocks. Hence, a potential area for further work will be the combination of CGV with Priority GV [5, 4] to restore deadlock-freedom and tie the system back to logic. Additionally, we aim to explore channel sharing through different means, namely via manifest sharing [1].

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A Context Split

Typing environments can be split according to rules in Figure 1 analogously to the work done by Vasconcelos [6].

That allows all channels to be unrestricted while preserving linearity for everything else.

$$\begin{split} \overline{\varphi} &= \varphi \circ \varphi \\ \hline \Gamma &= \Gamma_1 \circ \Gamma_2 \qquad T = tr(\rho) \\ \overline{\Gamma, x: T} &= (\Gamma_1, x: T) \circ (\Gamma_2, x: T) \\ \hline \Gamma, x: T = (\Gamma_1, x: T) \circ \Gamma_2 \\ \hline \Gamma, x: T = (\Gamma_1, x: T) \circ \Gamma_2 \\ \hline \hline \Gamma, x: T = \Gamma_1 \circ (\Gamma_2, x: T) \\ \hline \end{array} \end{split}$$

Figure 1: Context split.

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B Static Typing Rules

Full static typing rules are presented in Figure 3 and Figure 3.

Values typing judgements

Typing judgements for values are of the form

 $\Gamma \vdash V : T$

which states that Under typing environment Γ , term V is of type T.

Computations typing judgements

Typing judgements for computations are of the form

 $\Gamma; C \vdash M : T \triangleright C'$

which states that Under typing environment Γ and with capability set C, term M is of type T and produces capability set C'.

T-VAR	T-Unit	Γ -LAM $\Gamma, x: T; C \vdash M: U \triangleright C$	\mathcal{C}'
$\overline{x:T\vdash x:T}$	$\varnothing \vdash (): 1$	$\overline{\Gamma \vdash \lambda x.M}: T\ (C) \multimap (C$	') U
	$\frac{\text{T-PairVal}}{\Gamma \vdash V : T}$	$\Delta \vdash W: U$	
	$\Gamma \circ \Delta \vdash (V,$	W):T imes U	
T-Inl Γ⊢	V:T	$\frac{\text{T-Inr}}{\Gamma \vdash \boldsymbol{V}: \boldsymbol{U}}$	
$\overline{\Gamma \vdash \mathbf{inl} \; V: T + U}$		$\Gamma \vdash \mathbf{inr} \; V: T + U$	

Figure 2: Static Typing Rules for Values.



Figure 3: Static Typing Rules for Computations.